

## Bibliography and Publications

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- <sup>12</sup>See for example Carvalho, M.F., Silva Filho, O. S. and Femandes, C.A.O. "O Planejamento da Manufatura - Praticas Industriais e Métodos de Otimização" in *Gestão & Produção*, v.5, n. 1, April 1998 pp.34-59).
- <sup>13</sup>See Erixon (1998), p.7.
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- <sup>18</sup>Walker, J.M. (ed.). *Handbook of Manufacturing Engineering*, Marcel Dekker Inc., 1996.
- <sup>19</sup>Chednmü et al. (199-7), pp.xvi-xvii
- <sup>20</sup>Gao, J.X. and Bennett, G.R. "Manufacturing Capability Modeling for Concurrent Product Development" in Chedmail et al. (op.cit).
- <sup>21</sup>This idea was suggested by Prof. Michel Minoux, Université de Paris (France) during a visit to the University of Southampton.
- <sup>22</sup>Mahbub, R. *Automation and Robotics in Construction*. Unpublished MSc Dissertation. University of Manchester, 1993.
- <sup>27</sup>Riemer, R- and Edan Y. "The Evaluation of the Influence of Target Locations on Robots". Working paper, Dept. of Industrial Engineering and Management, Ben-Gurion University of the Negev, 1999.
- <sup>28</sup>Billingsley, J. *Robots and Automated Manufacture*. IEEE Control Engineering Series. Short Run Press Ltd., 1985.
- <sup>29</sup>Fuller, 1992 (op. cit.), p. 171.
- <sup>30</sup>This sub-section of the report is largely based on inputs from A. Pashkevich (ROBOLAB, Belarus).
- <sup>31</sup>A robot simulation package called ROBOMAX with all of the features named below developed by ROBOLAB.
- <sup>32</sup>The repeatability of industrial robots tends to be higher than their accuracy, averaging 0.5 mm and 1.0 mm respectively.
- <sup>33</sup>Roy, Daniel. *Une architecture hierarchisee multi-Agents pour le pilotage reactif d'ateliers de Production*. Unpublished Ph.D. thesis, Université de Metz, 1998.
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- <sup>35</sup>Roy, D. 1998 (op.cit.), p. 18.
- <sup>36</sup>Roy, D. and Anciaux, D. "A Hierarchical Multi-agent Approach Applied to the Shop Floor Control". Proceedings of the CARS & FDF Conference, Colombia, Dec. 1997.
- <sup>37</sup>Graphical representation based on Roy, D. 1998, op.cit (pp. 34
- <sup>38</sup>Roy, D. 1998 (ap.cit.), p. 43.
- <sup>40</sup>The introductory section on Production Planning and Scheduling was largely based on contribution and bibliographic references provided by C.N. Potts from the University of Southampton (UK). The sub-section on plant layout was enlarged to include publications from the Université de Metz.
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- <sup>43</sup> See, for instance Yie, Xiaom. "Manufacturing Cell Formation under Capacity Constraints". *Applied Stochastic Models and Data Analysis*, vol. 9, 1993, pp. 87-96. Also Harhalakis, G., Proth, J.M. and Xie, X.L. "Manufacturing Cell Design using Simulated Annealing: an Industrial Application". *Journal of Intelligent Manufacturing* 1, 1990, pp. 185-191. Also Souilah A. "Theory and Methodology: Simulated Annealing for Manufacturing Systems Layout Design". *European Journal of Operations Research* 82, 1995 (pp. 592-614).
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- <sup>48</sup> Cundiff, E.W. and Hilger, M.T. *Marketing in the International Environment*. Prentice-Hall International Editions, 1988.
- <sup>49</sup> Cundiff and Hilger (1988), op.cit., p.350.
- <sup>50</sup> Fuller, J. (1992), op. cit., p. 171
- <sup>51</sup> Maintainability is a largely undefined design characteristic that measures the facility of access and repair of a given system, also being linked to system complexity as well as the ease, accuracy, safety and cost associated with the performance of maintenance actions.
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- <sup>54</sup> Blanchard, B. S. *Logistics Engineering and Management* Prentice-Hall International Series, 1986.
- <sup>55</sup> Common indicators for reliability and maintainability are mean time between failures and mean time to repair, respectively.
- <sup>56</sup> Dornier, P-P, Ernst R., Fender, M. and Kouvelis, P. *Global Operations and Logistics. Text and Cases*. John Wiley & Sons, 1998.
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